

T-EMU: GRSPW1 Model Manual



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1. Introduction

The GRSPW1 is part of the GRLIB IP library. It is available in libTEMUGrspw1.so.

2. Configuration

To work correctly, the device should be connected to an interrupt controller, the memory and another SpaceWire device.

There are several configuration parameters in the GrSpw1 device, summarized in the following table:

Name	Description
config.infiniteSpeed	With this set, messages are sent immediately instead of being scheduled for the future based on the message length. This is the default option.
config.transmitter.frequency	Specify the SpaceWire transmitter frequency in Hz. Affects transfer speed when infinite speed is disabled.
config.transmitter.dataRate	SpaceWire port datarate: 1=single, 2=double, etc. Affects transfer speed when infinite speed is disabled.
config.interrupt	Influences the interrupt that is raised with the IRQ controller (setting this property also updates the APB PnP info).
config.realCrcCheck	Set to use real crc check instead of packet crc flags. Real crc costs in terms of performance.

3. Attributes

3.1. Properties

Name	Type	Description
config.infiniteSpeed	uint8_t	Set to use infinite speed for transfers.
config.interrupt	uint8_t	The interrupt index
config.realCrcCheck	uint8_t	Set to use real crc check instead of packet crc flags
config.transmitter.dataRate	uint8_t	SpaceWire port datarate: 1=single, 2=double,...
config.transmitter.frequency	uint32_t	SpaceWire transmitter frequency in Hz
internal.linkState	int32_t	Link state
internal.txDAddr	uint32_t	Data address for the scheduled dma engine transfer
internal.txDLength	uint32_t	Data length for the scheduled dma engine transfer
internal.txFlags	uint32_t	Flags for the scheduled dma engine transfer
internal.txHAddr	uint32_t	Header address for the scheduled dma engine transfer
internal.txType	uint8_t	Scheduled transmission type (dma engine/rmap)
internal.uplinkNsPerByte	uint32_t	Transmitter speed
irqCtrl	iref / <unknown>	Irq controller
memory	iref / <unknown>	Memory used for DMA accesses
object.timeSource	object	Time source object (a cpu or machine object)
pnnp.bar	uint32_t	Pnp BAR
pnnp.config	uint32_t	Pnp configuration
regs.clockDiv	uint32_t	Clock Divisor register
regs.control	uint32_t	Control register
regs.destKey	uint32_t	Destination Key register
regs.dmaControl	uint32_t	Dma control registers
regs.dmaRxDescTableAddr	uint32_t	Dma receive descriptor table address registers
regs.dmaRxMaxLen	uint32_t	Dma rx maximum length registers



Name	Type	Description
regs.dmaTxDescTableAddr	uint32_t	Dma transmit descriptor table address registers
regs.nodeAddress	uint32_t	Node address register
regs.statusIrqSrc	uint32_t	Status / Interrupt-source register
regs.time	uint32_t	Time register
spwUplink	[2 x iref / <unknown>]	SpaceWire devices connected to the port

3.2. Interfaces

Name	Type	Description
ApbIface	ApbIface	Apb interface
DeviceIface	DeviceIface	Device interface
MemAccessIface	MemAccessIface	Memory Access Interface
ResetIface	ResetIface	
SpwPortIface	SpwPortIface	SpaceWire ports interfaces

3.3. Ports

Prop	Iface	Description
-	-	-

4. Limitations

The following limitations/deviations from real hardware are known to exist with this model:

- No spill is currently not implemented
- Although the device already provides two spacewire ports, dual port is not yet implemented. This correspond to a device where the port VHDL parameter is set to 1. Therefore, in the control register, PO will be 0 and PS / NP bit are not available. Let us know if you need this feature implemented.
- The link interface currently effectively uses only ErrorReset, Ready, Connecting and Run states. Therefore, those are the only values that will be visible on the status register.
- RMAPEN signals not available

5. Examples

This example shows how to create two Grspw1 devices and connect them.

```
import BusModels
```



```
import TEMUGrspw1
object-create class=Grspw1 name=grspw0
object-create class=Grspw1 name=grspw1
spw-connect port1=grspw0:SpwPortIface[0] port2=grspw1:SpwPortIface[0]
```